

10130 Lecture Notes

we know it's invertible if in REF and no row of all 0's, get into reduced echelon form

Ex) compute: $\begin{bmatrix} 2 & 5 & 0 & 0 \\ 1 & 3 & 1 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & -2 \end{bmatrix}^{-1} \rightarrow \begin{bmatrix} 2 & 5 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 3 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & -2 & 0 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 3 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & -2 & 0 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & -2 & 0 & 0 & 0 & 1 \end{bmatrix}$

Therefore, $A^{-1} = \begin{bmatrix} 3 & -5 & 10 & -5 \\ -1 & 2 & -4 & 2 \\ 0 & 0 & 2 & -1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$

r & c always b & c of eqn A is invertible Ax=b x=A^{-1}b

Big Theorem (v.3):

Let $A = \{a_1, \dots, a_n\}$ be a set of n vectors in \mathbb{R}^n , let $A = [a_1, \dots, a_n]$ and let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be given by $T(\vec{x}) = A\vec{x}$. Then the following are equivalent:

- a) A spans \mathbb{R}^n
 - b) A is linearly independent
 - c) $Ax=b$ has a unique solution for all b in \mathbb{R}^n
 - d) T is onto
 - e) T is 1-1
 - f) A is invertible
- a & b are always equivalent; b & c are always equivalent

Subspaces

• vectors making a plane in $\mathbb{R}^3 \neq \mathbb{R}^2$, e.g.

↳ that plane is a **subspace**

• **Definition:** A subset of \mathbb{R}^n is called a subspace if S satisfies the following conditions:

- a) $\vec{0}$ is in S ($0 \in S$) } means set can't be empty
- b) If \vec{u} and \vec{v} are in S then $\vec{u} + \vec{v}$ is in S
- c) If \vec{u} is in S & c is a scalar, then $c\vec{u}$ is in S

Ex) Let S be the set of vectors $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ with $x_1 + x_2 = 0$. Is S a subspace?

- a) $\vec{0}$ is in the set because $0+0=0 \Rightarrow$ a) ✓
- b) $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}, \vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \Rightarrow \vec{u} + \vec{v} = \begin{bmatrix} u_1 + v_1 \\ u_2 + v_2 \end{bmatrix}$ then $(u_1 + v_1) + (u_2 + v_2) \Rightarrow \underbrace{u_1 + u_2}_{0} + \underbrace{v_1 + v_2}_{0} = 0 + 0 = 0$ so $0+0=0 \Rightarrow$ b) ✓
- c) $cu_1 + cu_2 = 0 \Rightarrow c(u_1 + u_2) = 0 \Rightarrow cu$ is in $S \Rightarrow$ c) ✓

Therefore S must be a subspace (the line $y = -x$ in \mathbb{R}^2)

If changed to $x_1 + x_2 = 1$, is it still a subspace? No, because it no longer passes a) or passes through the origin

10/30 Lecture Notes (continued)

Theorem: Let $S = \text{span}(\vec{u}_1, \dots, \vec{u}_m)$ be a subset of \mathbb{R}^n . Then S is a subspace

Proof: a) $\vec{0} = 0\vec{u}_1 + \dots + 0\vec{u}_m$ so $\vec{0}$ is in S

b) let u and v in S so $\vec{u} = c_1u_1 + \dots + c_mu_m$ and $\vec{v} = d_1u_1 + \dots + d_mu_m$
 thus $\vec{u} + \vec{v} = (c_1 + d_1)u_1 + \dots + (c_m + d_m)u_m$ so $u + v$ is in S

c) $c\vec{u} = cc_1u_1 + \dots + cc_mu_m$ so $c\vec{u}$ is in S thus S is a subspace

Ex 1 Let $A = \begin{bmatrix} 1 & 0 & 1 \\ 2 & -1 & -2 \end{bmatrix}$ let S be the set of solutions to $A\vec{x} = \vec{0}$. Is S a subspace?

$$\left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 2 & -1 & -2 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & 1 & 0 \\ 0 & -1 & -4 & 0 \end{array} \right]$$

$$x_3 = \text{free variable} = s_1 \quad \left. \begin{array}{l} x_2 = -4s_1 \\ x_1 = -s_1 \end{array} \right\} \vec{x} = s_1 \begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix}$$

$$S = \text{span} \left(\begin{bmatrix} -1 \\ -4 \\ 1 \end{bmatrix} \right)$$

(the set of solutions to $Ax=0$ is a subspace as well)

Theorem: If A is an $n \times m$ matrix then the set of solutions to $Ax=0$ is a subspace of \mathbb{R}^m

Proof: a) $A\vec{0} = \vec{0}$ so $\vec{0}$ is in S

b) Suppose $Au=0$ and $Av=0$ then $A(u+v) = Au + Av$
 $= \vec{0} + \vec{0} = \vec{0}$

c) $A(c\vec{u}) = c(A\vec{u}) = c\vec{0} = \vec{0}$

(If it satisfies all 3 conditions then it is a subspace)